

Mark Scheme (Results)

October 2023

Pearson Edexcel International Advanced Subsidiary Level in Physics (WPH11) Paper 01 Unit 1: Mechanics and Materials

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- All candidates must receive the same treatment. Examiners must mark the first candidate in exactly the same way as they mark the last.
- Mark schemes should be applied positively. Candidates must be rewarded for what they have shown they can do rather than penalised for omissions.
- Examiners should mark according to the mark scheme not according to their perception of where the grade boundaries may lie.
- There is no ceiling on achievement. All marks on the mark scheme should be used appropriately.
- All the marks on the mark scheme are designed to be awarded. Examiners should always award full marks if deserved, i.e. if the answer matches the mark scheme. Examiners should also be prepared to award zero marks if the candidate's response is not worthy of credit according to the mark scheme.
- Where some judgement is required, mark schemes will provide the principles by which marks will be awarded and exemplification may be limited.
- When examiners are in doubt regarding the application of the mark scheme to a candidate's response, the team leader must be consulted.
- Crossed out work should be marked UNLESS the candidate has replaced it with an alternative response.

Question Number	Answer	Mark
1	A is the correct answer	1
	D is in connect because displacement is a substan	
	B is incorrect because displacement is a vector C is incorrect because mass is a scaler	
	D is incorrect because velocity is a vector	
2	A is the correct answer	1
	B is incorrect because this is an SI unit of force	
	C is incorrect because this is an SI unit of acceleration	
3	D is incorrect because units of momentum are usually either kg m s ⁻¹ or N s B is the correct answer	1
3	b is the correct answer	1
	A is incorrect because Hooke's law is when force \propto extension	
	C is incorrect because the elastic limit relates to what happens when the	
	deforming force is removed	
	D is incorrect because this is the breaking stress	
4	C is the correct answer	1
	A is incorrect because this would be stationary B is incorrect because this would be constant velocity	
	D is incorrect because this would be a decreasing velocity	
5	C is the correct answer	1
-		
	A is incorrect because the force of gravity is down and the helicopter is	
	going up	
	B is incorrect because this includes increasing kinetic energy	
	D is incorrect because this is the increase in kinetic energy	
6	A is the correct answer	1
	B is incorrect because $E_k \propto v^2$ or $v \propto \sqrt{E_k}$ if $2E_k$ then $v_{\text{new}} = \sqrt{2}v$	
	C is incorrect because $E_k \propto v^2$ or $v \propto \sqrt{E_k}$ if $2E_k$ then $v_{\text{new}} = \sqrt{2}v$	
	D is incorrect because $E_k \propto v^2$ or $v \propto \sqrt{E_k}$ if $2E_k$ then $v_{\text{new}} = \sqrt{2}v$	
7	A is the correct answer	1
	D is incompatible useful output $= 2.1$ CW and total input $= 2.4 \pm 2.1$	
	B is incorrect because useful output = 2.1 GW and total input = $2.4 + 2.1$ GW	
	C is incorrect because useful output = 2.1 GW and total input = $2.4 + 2.1$	
	GW	
	D is incorrect because useful output = 2.1 GW and total input = $2.4 + 2.1$	
	GW	
8	A is the correct answer	1
	\mathbf{D}	
	B is incorrect because stress \propto strain or $F/A \propto \Delta x/x$ or $\Delta x \propto x/d^2$ if $2\Delta x$	
	then $0.5x / (0.5 d)^2 = 2 (x/d^2)$ C is incorrect because stress \propto strain or $F/A \propto \Delta x/x$ or $\Delta x \propto x/d^2$ if $2\Delta x$	
	then $0.5x / (0.5 d)^2 = 2 (x/d^2)$	
	D is incorrect because stress \propto strain or $F/A \propto \Delta x/x$ or $\Delta x \propto x/d^2$ if $2\Delta x$	
	then $0.5x / (0.5 d)^2 = 2 (x/d^2)$	
9	D is the correct answer	1
	A is incorrect because the addition of vector forces on an object in	
	equilibrium = 0	
	B is incorrect because the addition of vector forces on an object in	
	equilibrium = 0 C is incorrect because the addition of vector forces on an object in	
	C is incorrect because the addition of vector forces on an object in equilibrium $= 0$	
	Cyumonum – C	

10	B is the correct answer	1
	A is incorrect because $W = F \cos \theta \times d$	
	C is incorrect because $W = F \cos \theta \times d$	
	D is incorrect because $W = F \cos \theta \times d$	

Question Number	Answer		Mark
11(a)	Use of $W = mg$	(1)	
	Use of $F = ma$	(1)	
	$a = 4.8 \text{ m s}^{-2}$	(1)	3
	Example calculation $W = 5.0 \times 10^{6} \text{kg} \times 9.81 \text{ N kg}^{-1} = 4.91 \times 10^{7} \text{ N}$ $\Sigma F = 7.3 \times 10^{7} \text{ N} - 4.91 \times 10^{7} \text{kg} = 5.0 \times 10^{6} \text{ kg} \times a$ $a = \frac{2.39 \times 10^{7} \text{ N}}{5.0 \times 10^{6} \text{ kg}} = 4.78 \text{ m s}^{-2}$		
11(b)	The mass / weight of the rocket / fuel decreases (because fuel is used up) Or The thrust force increases Or		
		(1)	1
	Total for question 11		4

Question Number	Answer		Mark
12(a)	Total momentum before (a collision) = total momentum after (a collision) Or total momentum remains constant When no external force acts	(1)	
	Or When no resultant force acts on the system Or In a closed / isolated system	(1)	2
12(b)(i)	Momentum is mass \times velocity and after the collision the mass (that is moving) is double the original value.	(1)	
	(because velocity is half its original value) momentum remains the same so the law is obeyed (dependent on MP1) OR	(1)	2
	Initial momentum of A is equated to final momentum of A plus final momentum of B	(1)	
	Shows that MP1 is consistent with final velocity = half initial velocity and concludes that the law is obeyed (dependent on MP1)	(1)	
12(b)(ii)	 (The gliders accelerate in opposite directions because) the magnetic forces are equal in size and opposite in direction Or (The gliders accelerate in opposite directions because) the magnetic forces form a Newton's 3rd law pair 	(1)	
	So the velocity of one glider increases and the velocity of the other decreases (by the same amount) Or So the resultant force on the system is zero		
	Or The magnetic forces are not external forces	(1)	2
	Total for question 12		6

Question Number	Answer		Mark
13(a)(i)	Use of $s = ut + \frac{1}{2} at^2$	(1)	
	t = 0.72 (s)	(1)	2
	Example calculation 2.54 m = $(0 \times t) + \frac{1}{2} \times 9.81$ m s ⁻² × t^2 t = 0.72 s		
13(a)(ii)	Use of $s = ut + \frac{1}{2} at^2$ with $a = 0$	(1)	
	$u = 25 \text{ m s}^{-1}$ [ecf from (a)(i)] [Show that value gives 25.6 m s ⁻¹]	(1)	2
	$\frac{\text{Example calculation}}{u_{\rm H} = \frac{17.89 \text{m}}{0.72 \text{s}}} = 24.8 \text{m s}^{-1}$		
13(b)	(If the initial velocity is increased) the horizontal (component of) velocity is larger	(1)	
	The vertical (component of) velocity as the ball hits the ground is not affected	(1)	
	(When θ is the angle to the horizontal), $\tan(\theta) = \frac{v_V}{v_H}$ so θ decreases		
	Or (When θ is the angle to the vertical), $\tan(\theta) = \frac{v_{\rm H}}{v_{\rm V}}$ so θ increases		
	Or Labelled vector diagram showing how the angle changes if initial velocity of ball is increased.	(1)	3
	Total for question 13		7

Question Number	Answer		Mark
14(a)	Straight arrow at least 6 cm long representing F , with label	(1)	
	Vector triangle drawn with at least two sides in the triangle labelled, and F on the longest side.	(1)	
	All three arrows in correct relative directions (dependent on MP2)	(1)	4
	T = 70 N (allow range of 65 to 75 N)	(1)	•
	Example vector diagram		
	F 30° 30° T		
14(b)	Use of $\Delta W = F \Delta s$	(1)	
	Use of $P = W / t$ (allow	(1)	
	P = 28 (W), which is not equal to 35 (W), so is not consistent	(1)	3
	[Use of $v = \frac{s}{t}$ [1]		
	Use of $P = Fv$ [1]		
	P = 28 W which is not equal to 35 W, so is not consistent [1]]		
	Allow approaches that work backwards from 35W to determine time, number of repetitions, force applied or vertical distance moved.		
	Example calculation $\Delta W = 150 \text{ N} \times 0.25 \text{ m} = 37.5 \text{ J}$ $P = \frac{37.5 \text{ J} \times 90}{120 \text{ s}} = 28.1 \text{ W}$		
	Total for question 14		7

Question Number	Answer		Mark
15(a)	Point through which weight may be taken to act	(1)	1
15(b)(i)	Determines distance from hinge to centre of gravity of ladder (0.50 m)	(1)	
	Use of moment = Fx	(1)	
	Moment (of weight of ladder about hinge) = $27 (N m)$ and		
	moment (of weight of board about hinge) = 22.5 (N m)		
	Or combined moment (of weight of ladder and board about hinge) = 4.5 (N m)	(1)	
	Combined moment (of the weights of the board and ladder about the hinge) is clockwise. Or		
	clockwise moment is greater than anticlockwise moment	(1)	
	The block causes a force / moment so the resultant moment (on ladder and board) is zero	(1)	5
	Example calculation Distance from hinge to centre of gravity of ladder = $\left(\frac{2.7 \text{ m}}{2} - 0.85 \text{ m}\right)$ Clockwise moment = 54 N × (0.50 m) = 27 N m Anticlockwise moment 50 N × 0.45 m = 22.5 N m		
15(b)(ii)	Use of moment = Fx and difference in moments from (b)(i)	(1)	
	Force = 5.6 N (ecf from(b)(i))	(1)	2
	If no other mark scored, allow 1 mark for a force calculated using a distance of 0.80 m with a valid moment using data from the question		
	Example calculation Resultant moment = 27 N m - 22.5 N m = 4.5 N m $F = \frac{4.5 \text{ N m}}{0.80 \text{ m}} = 5.63 \text{ N}$		
	Total for question 15		8

They are not the same type of force(1)2 16(b)(i) Use of $\varepsilon = \frac{\Delta x}{x}$ (1)Use of $F = k\Delta x$ and $\sigma = \frac{F}{A}$ (1)Use of $E = \frac{\sigma}{\varepsilon}$ [allow a method using $E = \frac{kx}{A}$ for 3 marks](1) $E = 2.1 \times 10^{11}$ Pa(1) $\Delta x = 3 \times 10^{-4} \times 3.8$ m = 1.14 × 10 ⁻³ m(1) $F = 2.8 \times 10^7$ N m ⁻¹ × 1.14 × 10 ⁻³ m = 3.19 × 10^4 N $\sigma = \frac{3.19 \times 10^4}{5.1 \times 10^{-4} \text{ m}^2} = 6.26 \times 10^7$ Pa $E = \frac{6.26 \times 10^7 \text{ Pa}}{3.0 \times 10^{-4}} = 2.09 \times 10^{11}$ Pa	Question Number	Answer	Mark
16(b)(i) Use of $\varepsilon = \frac{\delta x}{x}$ (1) Use of $F = k\Delta x$ and $\sigma = \frac{F}{A}$ (1) Use of $F = k\Delta x$ and $\sigma = \frac{F}{A}$ (1) Use of $E = \frac{e}{\varepsilon}$ [allow a method using $E = \frac{kx}{A}$ for 3 marks] (1) $E = 2.1 \times 10^{11}$ Pa (1) $E = 2.1 \times 10^{11}$ Pa (2) $E = 2.1 \times 10^{11}$ Pa (2) $E = 2.1 \times 10^{11}$ Pa (2) $\Delta x = 3 \times 10^{2}$ N m ⁻¹ × 1.14 × 10 ⁻³ m = 3.19 × 10 ⁴ N $\sigma = \frac{3.19 \times 10^{14}}{5.10^{14} \text{ m}^2} = 6.26 \times 10^{7}$ Pa $E = \frac{6.26 \times 10^{7}}{3.0 \times 10^{-4}} = 2.09 \times 10^{11}$ Pa (1) Weight of electromagnet is still exerted on cable after object falls (can be indicated on graph) (1) So change in elastic strain energy = area under graph between total weight (of electromagnet is still exerted on cable after object falls (can be shown on graph or given as an algebraic equivalent using $E_{e1} = \frac{1}{2}F\Delta x$ (1) And change in gravitational potential energy of electromagnet is weight of electromagnet × change in extension (can be indicated on graph) (1) So the change in elastic strain energy stored > change in gravitational potential energy of the electromagnet (can be indicated on graph) (1) So the change in elastic strain energy stored > change in gravitational potential energy of the electromagnet (can be indicated on graph) (1) So the change in elastic strain energy stored > change in gravitational potential energy of the electromagnet (1) Example of graph F $total weight of electromagnet (2) change in gravitational potential energy is the electromagnet (1) for a least end steries train energy weight of electromagnet (1) for a least end steries train energy is the electromagnet (1) for a least end the electromagnet (1) for a least end steries train energy weight of electromagnet (1) for a least end steries train energy weight of electromagnet (1) for a least end steries train energy (1) for$	16(a)	They act on the same object (1)	
Use of $F = k\Delta x$ and $\sigma = \frac{F}{A}$ (1) Use of $F = k\Delta x$ and $\sigma = \frac{F}{A}$ (1) Use of $F = \frac{\sigma}{c}$ [allow a method using $E = \frac{kx}{A}$ for 3 marks] (1) $E = 2.1 \times 10^{11}$ Pa (1) Example calculation $\Delta x = 3 \times 10^{-4} \times 3.8 m = 1.14 \times 10^{-3}$ m $A = 3.19 \times 10^{4}$ N $\sigma = \frac{3.19 \times 104}{5.120^{-4} \text{ m}^{2}} = 6.26 \times 10^{7}$ Pa $E = \frac{6.26 \times 10^{7}}{3.0 \times 10^{-4}} = 2.09 \times 10^{11}$ Pa I6(b)(ii) Area under graph = elastic strain energy (can be indicated on graph) (1) Weight of electromagnet is still exerted on cable after object falls (can be indicated on graph) (1) So change in elastic strain energy = area under graph between total weight (of electromagnet and steel object) and weight of electromagnet (can be shown on graph or given as an algebraic equivalent using $E_{el} = \frac{1}{2}F\Delta x$ (1) And change in gravitational potential energy of electromagnet is weight of electromagnet × change in extension (can be indicated on graph) (1) So the change in elastic strain energy stored > change in gravitational potential energy of the electromagnet (and be indicated on graph) (1) So the change in elastic strain energy stored > change in gravitational potential energy of the electromagnet (1) Example of graph F total weight of electromagnet (1) F total weight of (They are not the same type of force (1)	2
Use of $F = k\Delta x$ and $\sigma = \frac{1}{A}$ Use of $E = \frac{\sigma}{e} [allow a method using E = \frac{kx}{A} for 3 marks] (1)E = 2.1 \times 10^{11} \text{ Pa} (1)E = 2.1 \times 10^{11} \text{ Pa} (1)E = 2.1 \times 10^{11} \text{ Pa} (1)\Delta x = 3 \times 10^{-4} \times 3.8 \text{ m} = 1.14 \times 10^{-3} \text{ m}\Delta x = 3 \times 10^{-4} \times 3.8 \text{ m} = 1.14 \times 10^{-3} \text{ m} = 3.19 \times 10^{4} \text{ N}\sigma = \frac{3.19 \times 10^{-4}}{5.110^{-4} \text{ m}^{2}} = 6.26 \times 10^{7} \text{ Pa}E = \frac{6.26 \times 10^{7}}{3.0 \times 10^{-4} \text{ m}^{2}} = 2.09 \times 10^{11} \text{ Pa}16(b)(ii) Area under graph = elastic strain energy (can be indicated on graph) (1)Weight of electromagnet is still exerted on cable after object falls (can be indicated on graph) (1)So change in elastic strain energy = area under graph between total weight (of electromagnet and steel object) and weight of electromagnet (can be shown on graph or given as an algebraic equivalent using E_{el} = \frac{1}{2}F\Delta x (1)And change in gravitational potential energy of electromagnet is weight of electromagnet × change in extension (can be indicated on graph) (1)So the change in elastic strain energy stored > change in gravitational potential energy of the electromagnet (1)So the change in elastic strain energy stored > change in gravitational potential energy of the electromagnet (1)So the change in elastic strain energy stored > change in gravitational potential energy in elastic strain energy in e$	16(b)(i)	Use of $\varepsilon = \frac{\Delta x}{r}$ (1)	
$E = 2.1 \times 10^{11} \text{ Pa} $ (1) $E = 2.1 \times 10^{11} \text{ Pa} $ (1) $\frac{E = 2.1 \times 10^{11} \text{ Pa}}{\Delta x = 3 \times 10^{-4} \times 3.8 \text{ m} = 1.14 \times 10^{-3} \text{ m}}{\Delta x = 3 \times 10^{-4} \times 3.8 \text{ m} = 1.14 \times 10^{-3} \text{ m}} = 3.19 \times 10^{4} \text{ N}$ $\frac{319 \times 104}{\sigma = \frac{319 \times 104}{3.1810^{-4} \text{ m}^{2}}} = 6.26 \times 10^{7} \text{ Pa}$ $E = \frac{626 \times 10^{7} \text{ Pa}}{3.0 \times 10^{-4}} = 2.09 \times 10^{11} \text{ Pa}$ 16(b)(ii) Area under graph = elastic strain energy (can be indicated on graph) (1) Weight of electromagnet is still exerted on cable after object falls (can be indicated on graph) (1) So change in elastic strain energy = area under graph between total weight (of electromagnet and steel object) and weight of electromagnet (can be shown on graph or given as an algebraic equivalent using $E_{el} = \frac{1}{2}F\Delta x$) (1) And change in gravitational potential energy of electromagnet is weight of electromagnet × change in extension (can be indicated on graph) (1) So the change in elastic strain energy stored > change in gravitational potential energy of the electromagnet (1) So the change in delatic strain energy stored > change in gravitational potential energy in elastic strain energy is determined to a graph (1) So the change in delatic strain energy stored > change in gravitational potential energy of the electromagnet (1) So the change in delatic strain energy stored > change in gravitational potential energy in elastic strain energy in el		Use of $F = k\Delta x$ and $\sigma = \frac{F}{A}$ (1)	
$E = 2.1 \times 10^{-1} \text{ Pa}$ Example calculation $\Delta x = 3 \times 10^{-4} \times 3.8 \text{ m} = 1.14 \times 10^{-3} \text{ m} = 3.19 \times 10^{4} \text{ N}$ $F = 2.8 \times 10^{7} \text{ Nm}^{-1} \times 1.14 \times 10^{-3} \text{ m} = 3.19 \times 10^{4} \text{ N}$ $\sigma = \frac{3.19 \times 104 \text{ N}}{5.1 \times 10^{-4} \text{ m}^{2}} = 6.26 \times 10^{7} \text{ Pa}$ $E = \frac{6.26 \times 10^{7} \text{ Pa}}{3.0 \times 10^{-4}} = 2.09 \times 10^{11} \text{ Pa}$ 16(b)(ii) Area under graph = elastic strain energy (can be indicated on graph) (1) Weight of electromagnet is still exerted on cable after object falls (can be indicated on graph) (2) So change in elastic strain energy = area under graph between total weight (of electromagnet and steel object) and weight of electromagnet (can be shown on graph or given as an algebraic equivalent using $E_{et} = \frac{1}{2}F\Delta x$ (1) And change in gravitational potential energy of electromagnet is weight of electromagnet × change in extension (can be indicated on graph) (1) So the change in elastic strain energy stored > change in gravitational potential energy of the electromagnet (1) So the change in graph F total weight of graph F total weight of graph F total weight of graph F total weight of electromagnet (1) Area of small triangle plus rectangle = change in elastic strain energy in elastic strai		Use of $E = \frac{\sigma}{\varepsilon}$ [allow a method using $E = \frac{kx}{A}$ for 3 marks] (1)	
$\frac{\Delta x = 3 \times 10^{-4} \times 3.8 \text{ m} = 1.14 \times 10^{-3} \text{ m}}{F = 2.8 \times 10^7 \text{ m}^{-1} \times 1.14 \times 10^{-3} \text{ m} = 3.19 \times 10^4 \text{ N}}$ $\sigma = \frac{3.192104 \text{ N}}{51 \times 10^{-4} \text{ m}^2} = 6.26 \times 10^7 \text{ Pa}$ $E = \frac{6.26 \times 10^7 \text{ Pa}}{3.0 \times 10^{-4}} = 2.09 \times 10^{11} \text{ Pa}$ 16(b)(ii) Area under graph = elastic strain energy (can be indicated on graph) (1) Weight of electromagnet is still exerted on cable after object falls (can be indicated on graph) (1) So change in elastic strain energy = area under graph between total weight (of electromagnet and steel object) and weight of electromagnet (can be shown on graph or given as an algebraic equivalent using $E_{et} = \frac{1}{2}F\Delta x$ (1) And change in gravitational potential energy of electromagnet is weight of electromagnet × change in extension (can be indicated on graph) (1) So the change in elastic strain energy stored > change in gravitational potential energy of the electromagnet (1) So the change in deastic strain energy stored > change in gravitational potential energy in electromagnet (1) F total weight of electromagnet (1) Example of graph weight of electromagnet (1) Area of small triangle plus rectangle = change in elastic strain energy in electromagnet in energy in electromagnet in elastic strain energy in electromagnet (1) Example of graph Meight of electromagnet (1) Area of rectangle = change in elastic strain energy in elastic strain ener		$E = 2.1 \times 10^{11} \mathrm{Pa}$ (1)	4
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potential energy of the electromagnet (1) 5 Example of graph F total weight of electromagnet weight of electromagnet F F F F F F F F			
F total weight of electromagnet and steel object weight of electromagnet F Area of small triangle plus rectangle = change in elastic strain energy Area of rectangle represents change in GPE			5
total weight of electromagnet and steel object weight of electromagnet Weight of electromagnet		Example of graph	
		total weight of electromagnet and steel object weight of electromagnet Area of small triangle plus rectangle = change in elastic strain energy Area of rectangle represents change in GPE	
Total for question 16 11		Total for question 16	11

Question Number	Answer		Mark
17(a)	An upwards force caused by the displacement of fluid (by an object) Or		
	(a force equal and opposite to) the weight of fluid displaced (by an object)		
		(1)	1
17(b)(i)	Use of $\rho = \frac{m}{v}$ and $W = mg$ to calculate upthrust	(1)	
	Use of $\Sigma F = ma$	(1)	
	W = 13.2 (N)	(1)	3
	$\frac{\text{Example calculation}}{U = 1.63 \text{ m}^3 \times 1.23 \text{ kg m}^{-3} \times 9.81 \text{ N kg}^{-1} = 19.67 \text{ N}}$ $\Sigma F = 19.67 \text{ N} - \text{m} \times 9.81 = \text{m} \times 4.80 \text{ m s}^{-2}$ $m = \frac{19.7 \text{ N}}{4.80 \text{ N kg}^{-1} + 9.81 \text{ m s}^{-2}} = 1.346 \text{ kg}$ $W = 1.346 \text{ kg} \times 9.81 \text{ N kg}^{-1} = 13.20 \text{ N}$		
17(b)(ii)	Density at 25 km = 0.05 kg m ⁻³ (range $0.040 - 0.050$ kg m ⁻³)	(1)	
	Use of $W = mg$ and $\rho = m / V$	(1)	
	Volume required at 25 km = 27 m ³ (range 26 m ³ to 34 m ³) [show that value gives 26.5 m ³] [allow ecf from b(i)] Or Upthrust from a balloon of volume 50 m ³ at 25 km = 25 N (range 19.6 to		
	25.0 N)	(1)	
	Valid conclusion from comparison of their calculated volume with 50 m ³ Or Valid conclusion from comparison of their calculated upthrust with weight		
	of balloon <u>Example calculation</u> Upthrust required = 13.2 N = 0.05 kg m ⁻³ × 9.81 N kg ⁻¹ × V $V = 13.2 \text{ N} \div 0.491 \text{ N} \text{ m}^{-3} = 26.9 \text{ m}^{3}$ 26.9 m ³ < 50 m ³ so yes	(1)	4

	structured an		student's ability to inkages and fully-s				
	Marks are aw	varded for i	ndicative content a	nd for how the a	nswer is		
	structured an	d shows lin	es of reasoning.				
	The followin content and l	-	ws how the marks s coning.	should be award	ed for indicative		
	IC points	IC mark	Max linkage mark available	Max final mark]		
	6	4	2	6			
	5	3	2	5	4		
	4 3	3	1	4	-		
	2	2 2	1 0	3	-		
	1	1	0	1			
	0	0	0	0			
					Marks		
	and fully su throughout	stained line	ent and logical strue es of reasoning dem	ionstrated	ges 2		
	reasoning						
	Answer has	no linkage	s between points ar	nd is unstructure	d 0		
	Indicative co	ontent:					
	IC1 (When the	he balloon i	is released) upthrus	t greater than we	eight		
		he balloon i	-	t greater than we	eight		
	IC1 (When the IC2 the result IC3 Velocity	he balloon i tant force is of balloon	s upward	t greater than we	eight		
	IC1 (When the IC2 the result IC3 Velocity Or ballow IC4 (after ballow)	he balloon i tant force is of balloon oon accelera lloon is at r	s upward increases	Upthrust decrea	ses as height		
	IC1 (When the IC2 the result IC3 Velocity Or ballot IC4 (after ballot increased)	he balloon i tant force is of balloon oon accelera lloon is at r s (because o thrust is les	s upward increases ates (upwards) naximum volume)	Upthrust decreasing air decreases	ses as height s)		
	IC1 (When the IC2 the result IC2 the result IC3 Velocity Or ballow IC4 (after ballow IC4 (after ballow IC5 Until up) downward IC6 Velocity	he balloon i tant force is of balloon oon accelera lloon is at r s (because o thrust is les rds	s upward increases ates (upwards) naximum volume) density of surround	Upthrust decreasing air decreases ere is a resultant	ses as height s)	6	
	IC1 (When the IC2 the result IC2 the result IC3 Velocity Or ballow IC4 (after ballow IC4 (after ballow IC5 Until up) downward IC6 Velocity	he balloon is tant force is of balloon oon accelera lloon is at r s (because of thrust is les rds of balloon oon then dec	s upward increases ates (upwards) naximum volume) density of surround s than weight so the then decreases to z celerates to rest.	Upthrust decreasing air decreases ere is a resultant	ses as height s)	6	

Question Number	Answer		Mark
18 (a)	Small spherical object		
	Or Spherical object moving at low speed	(1)	
	Laminar flow [allow non-turbulent flow]	(1)	2
18(b)(i)	Max 3		
	Initially the velocity is zero so gradient is zero	(1)	
	As velocity increases the gradient changes	(1)	
	As velocity increases, drag increases	(1)	
	Until terminal / constant velocity when the gradient becomes constant.	(1)	3
	[If no other mark scored, allow 1 mark for velocity increases until terminal velocity is reached.]		
18(b)(ii)	Determines radius of ball bearing	(1)	
	Determines gradient	(1)	
	Use of $F = 6\pi\eta rv$	(1)	4
	$\eta = 0.046$ (Pa s) [allow a range from 0.044 (Pa s) to 0.048 (Pa s)]	(1)	
	Example calculation Radius = $\frac{1.6 \times 10^{-3} \text{ m}}{2} = 8 \times 10^{-4} \text{ m}$ Gradient = $\frac{\frac{1.6}{11.5}}{\frac{1.15 - 0.60}{1.15 - 0.60}} = 20.9$ $v = 0.209 \text{ m s}^{-1}$ 1.45 × 10 ⁻⁴ N		
	$\eta = \frac{1}{6\pi \times 8 \times 10^{-4} \text{ m} \times 0.209 \text{ m s}^{-1}} = 0.0460 \text{ Pa s}$		
18(b)(iii)	At higher temperature the viscosity will be less	(1)	
	$F = 6\pi\eta rv$ and r is constant	(1)	
	Drag force is less (at a given speed) Or		
	Drag force (at terminal velocity) is unchanged	(1)	
	Terminal velocity is greater (and ball-bearing takes less time to fall)	(1)	4
	Total for question 18		13

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